Branching vs. Linear Time: Final Showdown

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Formal Verification Today

Verification as debugging: *Failure* of verification identifies bugs.

- Both specifications and programs attempt to formalize informal requirements.
- Verification contrasts two independent formalizations.
- Failure of verification reveals inconsistency between the two formalizations.

Model checking: uncommonly effective debugging tool

- a systematic exploration of the design state space
- good at catching difficult "corner cases"

Designs are Labeled Graphs

Key Idea: Designs can be represented as transition systems (finite-state machines)

Transition System: $M = (W, I, R, F, \pi)$

- W: states
- $I \subseteq W$: initial states
- $R \subseteq W \times W$: transition relation
- $F \subseteq W$: fair states
- $\pi: W \to Powerset(Prop)$: Observation function

Fairness: An assumption of "reasonableness" - restrict attention to computations that visit F infinitely often, e.g., "the channel will be up infinitely often".

Specifications

Linear-Time Specifications: properties of computations.

Examples:

- "No two processes can be in the critical section at the same time." – safety
- "Every request is eventually granted." *liveness*
- "Every continuous request is eventually granted."
 liveness
- "Every repeated request is eventually granted." liveness

Linear Temporal Logic

Linear Temporal logic (LTL): logic of temporal sequences

Main feature: time is implicit

- $next \varphi$: φ holds in the next state.
- eventually φ : φ holds eventually
- always φ : φ holds from now on
- φ until ψ : φ holds until ψ holds.

Examples

- always not (CS₁ and CS₂): mutual exclusion (safety)
- always (Request implies eventually Grant): liveness
- always (Request implies Request until Grant): liveness
- always eventually Request implies eventually Grant: liveness

Linear vs. Branching

- Linear time: a system generates a set of computations
- Specs: describe computations

- Branching time: a program generates a computation tree
- *Specs*: describe computation trees

Program Equivalence

• *P*₁:

• *P*₂:

- Linear Time: $P_1 \equiv P_2$
- Branching Time: $P_1 \not\equiv P_2$

Temporal Logics

Specs: Every request is eventually granted

• Linear (LTL): always (Request implies eventually Grant)

Branching (CTL): ∀ always (Request implies ∀ eventually Grant)

LTL vs. CTL: The Long Debate

- Pnueli: 1977
- Lamport: "Sometimes' is sometimes 'Not Never"', 1980
- Emerson and Clarke: 1981
- Ben-Ari, Pnueli, and Manna: 1983
- Pnueli: 1985
- Emerson and Lei: "Branching-time logic strikes back", 1985
- Emerson and Halpern: "'Sometimes' and 'Not Never' Revisited", 1986

Conclusion: Philosophically, a draw.

LTL vs. CTL: Expressiveness

Caveat: Linear and branching logics are incomparable.

- LTL: eventually always P in every computation P is ultimately true.
- CTL: (∀ eventually ∀ always P) P will stabilize at true within a bounded amount of time.

General Assessment:

- Interesting CTL-LTL: "small"
- Interesting LTL-CTL: "large"

LTL vs. CTL: Complexity

Model-Checking Problem: Does T satisfy φ ?

$$|T|=n$$
, $|arphi|=m$

Time Complexity:

- *CTL*: O(nm) [CES'86]
- $LTL: O(n2^m)$ (PSPACE-complete) [LP'86,SC'85]

Conclusions:

- ullet Low complexity in |T|
- CTL exponentially easier than LTL

Pragmatics

Folk Wisdom: *CTL* is less expressive than *LTL*, but *CTL* is superior to *LTL* computationally.

Model Checking in practice: CTL usage dominates

- CTL: SMV, VIS, RuleBase, CheckOff, Motorola
- Linear Time: Cadence's SMV, FormalCheck, SPIN, Intel

Note: Linear Time \neq LTL!

CTL vs. LTL: A Fresh Perspective

- Expressiveness
- Computational Complexity
- Compositionality
- Pragmatics

Expressiveness

IBM's Experience:

• IBM J. of Research and Development: Formal Verification Made Easy, 1997

"We found only simple *CTL* equations to be intuitively comprehensible; nontrivial *CTL* equations are hard to understand and prone to error."

• CAV'98: On The-Fly Model Checking, 1998

"CTL is difficult to use for most users and requires a new way of thinking about hardware."

Fact: Sugar, RuleBase's spec language, tries to hide away CTL

Example:

- LTL: next eventually P, eventually next P
- CTL: \forall next \forall eventually P, \forall eventually \forall next P

Algorithmic Foundations

Basic Graph-Theoretic Problems:

- Reachability: Is there a finite path from I to F?
- ullet Fair Reachability: Is there an infinite path from I that goes through F infinitely often.

Note: These paths may correspond to error traces, e.g., *deadlock* and *livelock*.

CTL Model Checking

Basic Algorithm:

- Iterated reachability analysis (i.e., reachability and fair reachability)
- Simple recursion on structure of formulas, e.g., ∀ always ∃ eventually P involves a reachability computation followed by a fairreachability computation.
- Computational complexity is *linear* in size of design and size of spec.

Automata on Infinite Words

Büchi Automaton: $A = (\Sigma, S, S_0, \rho, F)$

- ullet Alphabet: Σ
- States: S
- Initial states: $S_0 \subseteq S$
- Transition relation: $\rho \subseteq S \times \Sigma \times S$
- Accepting states: $F \subseteq S$

Input word: a_0, a_1, \ldots

Run: s_0, s_1, \ldots

- $s_0 \in S_0$
- $(s_i, a_i, s_{i+1}) \in \rho$ for $i \ge 0$

Acceptance: F visited infinitely often

Temporal Logic vs. Automata

Paradigm: Compile high-level logical specifications into low-level finite-state language

The Compilation Theorem: [V.-Wolper]

Given an LTL formula φ , one can construct an automaton A_{φ} such that a computation σ satisfies φ if and only if σ is accepted by A_{φ} . Furthermore, the size of A_{φ} is at most exponential in the length of φ .

Example:

always eventually P:

• eventually always P

LTL Model Checking

The following are equivalent:

- M satisfies φ
- ullet all computations in L(M) satisfy arphi
- $L(M) \subseteq L(A_{\varphi})$
- $L(M||A_{\neg \varphi}) = \emptyset$

Bottom Line: To check that M satisfies φ , compose M with $A_{\neg \varphi}$ and check whether the composite system has a reachable (fair) path. Verification reduces to reachability or fair reachability.

Intuition: $A_{\neg \varphi}$ is a "watchdog" for "bad" behaviors. A reachable (fair) path means a bad behavior.

Computational Complexity

Worst case: linear in the size of the design space and exponential in the size of the specification.

Real life: Specification is given in the form of a list of properties $\varphi_1, \dots, \varphi_n$. It suffices to check that M satisfies φ_i for $1 \le i \le n$.

Moral: There is life after exponential explosion.

The real problem: too many design states – symbolic methods needed

CTL vs. LTL: Comparison

- Invalid Comparison: worst case of an inexpressive logic against worst case of an expressive logic
- Valid Comparison: competitive analysis compare performance of CTL and LTL model checkers on formulas that are in both logics
 - always eventually P
 - \forall always \forall eventually P

Empirical Claim: On formulas in LTL∩CTL, CTL and LTL model checkers behave similarly, and if they don't, you can make them (see work by Bloem-Ravi-Somenzi in CAV'99 and by Maidl in FOCS'00).

Compositional Verification

State Explosion:

- $\bullet \ T = T_1 || \dots || T_k$
- $\bullet |T| = |T_1| \cdot \ldots \cdot |T_k|$

$$\left. \begin{array}{l} P_1 \text{ satisfies } \psi_1 \\ P_2 \text{ satisfies } \psi_2 \\ C(\psi, \psi_1, \psi_2) \end{array} \right\} P_1 \| P_2 \text{ satisfies } \psi$$

- $P_1 \parallel P_2$: composition of P_1 and P_2
- $C(\psi,\psi_1,\psi_2)$: logical condition relating ψ , ψ_1 , and ψ_2

Advantage: apply model checking only to the underlying modules, which have smaller state spaces.

Assume-Guarantee Verification

M guarantees ψ assuming $\varphi - \langle \varphi \rangle M \langle \psi \rangle$: for an arbitrary M', if $M \| M' \models \varphi$, then $M \| M' \models \psi$

$$\left. \begin{array}{l} \langle \mathbf{true} \rangle M_1 \langle \varphi_1 \rangle \\ \langle \mathbf{true} \rangle M_2 \langle \varphi_2 \rangle \\ \langle \varphi_2 \rangle M_1 \langle \psi_1 \rangle \\ \langle \varphi_1 \rangle M_2 \langle \psi_2 \rangle \end{array} \right\} \langle \mathbf{true} \rangle M_1 \| M_2 \langle \psi_1 \wedge \psi_2 \rangle$$

Fact: Checking $\langle \varphi \rangle M \langle \psi \rangle$ is exponential in φ for both CTL and LTL [KV'95]

It Gets Worse!

CTL is too weak:

- *Crucial*: Assumptions have to be strong enough to ensure guarantee; *LTL* assumptions may be needed for a *CTL* guarantee.
- But: The combination of a CTL guarantee and an LTL assumption involves a doubly exponential cost in computational complexity.

In practice

- *CTL*-based model checkers do not support compositional reasoning
- Verifiers engage in unsafe reasoning when using CTL-based model checkers because assumptions are always needed.

Ken McMillan: "In compositional reasoning use LTL" (Cadence's SMV uses linear time).

Pragmatics

The linear-time view has numerous other advantages:

- Refinement: $L(T_{imp}) \subseteq L(T_{spec})$ linear view
- Abstraction: $L(T_{conc}) \subseteq L(T_{abst})$ linear view
- Dynamic validation: only linear view available
- Counterexamples: validators want traces
- Bounded Model Checking: Search linear counterexamples of predetermined size size.

What about Concurrency Theory?

But: CTL characterizes bisimulation!

So what?

- Bisimulation is about structure

 ∀ next ∀ eventually P vs. ∀ eventually ∀ next P
- Model checking is about behavior
 next eventually P vs. eventually next P
- Difference between ab+ac and a(b+c) become clear in a state-based model, in which deadlock is modeled explicitly

Is LTL The Answer?

Question: "Ok, ok. You made your point. Can we finish the talk and go with *LTL* then?"

Answer: "Not so fast. Let us reconsider compositional reasoning."

Compositional Reasoning Revisited

Crucial Points:

- Assume-guarantee reasoning is the prevalent way of reasoning about complicated systems – you always need assumptions.
- When trying to check that "M guarantees ψ assuming φ ", you can weaken ψ , but you have to make φ as strong as needed.

Corollary 1: Your spec language for *assumptions* needs to be as expressive as your hardware modeling language.

Crucial Point:

 Your assume-guarantee reasoning is not sound, unless you guarantee your assumptions – danger of false positives.

Corollary 2: Your spec language needs to be as expressive as your hardware modeling language.

Fact: *LTL* is too weak – cannot express finite-state machines.

Beyond Naive Hardware Modeling

Assumptions: abstracted hardware

Replace gorry detail by nondeterminism

Eliminate possible runs by using fairness

Note: Nondeterministic FSMs with fairness conditions are Büchi automata, which express ω -regularity (more expressive than LTL).

Question: Can we make Büchi automata into a spec language?

What Is Logic?

Features of Logic:

- Closure under Boolean connectives: if φ and ψ are formulas, then $\varphi \wedge \psi$, $\varphi \rightarrow \psi$ are formulas.
- Closure under substitution: atomic propositions can be replaced by formulas; if always p and eventually q are formulas, then always eventually q is a formula.

Extended Temporal Logic

ETL:

- Start with Büchi automata where the labels are atomic propositions
- Close under Boolean connectives (compositionality)
- Close under substitutions (re-usability)

Note: Closure under Boolean connectives and substitutions is not necessary for expressiveness. FormalCheck does not have it.

Example:

ETL: Pros and Cons

Advantages:

- Expressive enough for assume-guarantee reasoning
 Pnueli, 1986: "In order to perform compositional specification and verification, it is *necessary* to have the full power of *ETL*."
- Formalism (FSMs) is very familiar to hardware designers
- Worst-case complexity same as LTL.

Disadvantages:

- Nesting of machines is conceptually difficult
- No experimental validation (yet)
- Complementation is known to be difficult

Bottom Line: More research needed

Other Formalisms

- *μ*-calculus:
 - One temporal connective (next) plus fixpoint operators
 - Unreadable: always eventually P

$$(gfp \ X)(lfp \ Y)(X \land next(P \lor Y))$$

- QPTL:
 - LTL plus propositional quantifiers
 - Example:

$$(\exists X)(X \land always(X \leftrightarrow next \neg X) \land always(X \rightarrow P))$$

Complexity: nonelementary (unbounded stack of exponentials)!

A Pragmatic Proposal

Competing demands on real languages:

- Expressiveness: supports compositional reasoning
- Usability: can be used by verification engineers
- Closure: supports specification libraries
- Implementability: feasible implementation
- History: consistency with prior experience of users

FTL: ForSpec Temporal Logic

ForSpec: Intel's new formal specification language key features:

- linear-time logic, with fully ω -regularity
- rich set of operations of Boolean and arithmetical operations
- time windows (*P until* [10, 15] *Q*)
- regular events

$$always((req, (\neg ack)^*, ack) \ triggers$$
 $(true^+, grant, (\neg rel)^*, rel))$

- universal propositional quantification
- hardware-oriented features (multiple clocks and resets)

Did We Waste 20 Years on CTL?

Absolutely not!

- Usefulness of model checking demonstrated
- Symbolic reachability and fair reachability algorithms
- CTL model checkers as back-end for lineartime model checkers (Cadence's SMV and Intel's ForSpec)
- CTL is useful in checking correct modeling, e.g., $\forall \ always \ \exists \ true$ says that there is a fair path from every state.
- Branching time is appropriate in game-theoretic settings, e.g., Al planning and controller synthesis.

Conclusions

- In spite of 20 years of research, this issue has not been resolved yet
- CTL is clearly not adequate as a spec language
- LTL is better, but has weaknesses
- FTL is a strong industrial contender

My bottom line:

- Let's close the linear-time vs. branching time debate: linear time won!
- Let's re-open the linear-time vs. linear-time debate (e.g., FTL vs. FormalCheck vs. ITL).
- Let's develop linear-time model checking technology.